Previous Lecture:
- Nested loops
- Developing algorithms and code

Today’s Lecture:
- Review nested loops
- User-defined functions

Announcements:
- Project 2 due Monday at 11pm
- Upson Hall elevator out-of-service starting next week. Access for the physically disabled can be pre-arranged by emailing TA Pooja <pn226>
Rational approximation of $\pi$

- $\pi = 3.141592653589793\ldots$
- Can be closely approximated by fractions, e.g., $\pi \approx 22/7$
- Rational number: a quotient of two integers
- Approximate $\pi$ as $p/q$ where $p$ and $q$ are positive integers $\leq M$
- Start with a straightforward solution:
  - Get $M$ from user
  - Calculate quotient $p/q$ for all combinations of $p$ and $q$
  - Pick best quotient $\rightarrow$ smallest error
% Rational approximation of pi

M = input('Enter M: ');

% Check all possible denominators
% Rational approximation of pi

M = input('Enter M: ');

% Check all possible denominators
for q = 1:M

end
% Rational approximation of pi

M = input('Enter M: ');

% Check all possible denominators
for q = 1:M

    For current q find best numerator p...
    Check all possible numerators

end
% Rational approximation of pi

M = input('Enter M: ');

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M
        ...
    end
end
end
% Rational approximation of pi

M = input('Enter M: ');
% Best q, p, and error so far
qBest=1;   pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M

        end
    end

myPi = pBest/qBest;
% Rational approximation of pi

M = input('Enter M: ');
% Best q, p, and error so far
qBest=1;  pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
  % At this q, check all possible numerators
  for p = 1:M
    if abs(p/q - pi) < err_pq  % best p/q found
      err_pq = abs(p/q - pi);
pBest= p;
qBest= q;
    end
  end
end

myPi = pBest/qBest;
M = input('Enter M: ');
qBest=1; pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    p0=1; e0=abs(p0/q - pi); % best p & error for this q
    for p = 1:M
        if abs(p/q - pi) < e0 % new best numerator found
            p0=p; e0 = abs(p/q - pi);
        end
    end
    % Is best quotient for this q is best over all?
    if e0 < err_pq
        pBest=p0; qBest=q; err_pq=e0;
    end
end
myPi = pBest/qBest;
% Rational approximation of pi

M = input('Enter M: ');
% Best q, p, and error so far
qBest=1;  pBest=1;
err_pq = abs(pBest/qBest - pi);

% Check all possible denominators
for q = 1:M
    % At this q, check all possible numerators
    for p = 1:M
        if abs(p/q - pi) < err_pq  % best p/q found
            err_pq = abs(p/q - pi);
            pBest= p;
            qBest= q;
        end
    end
end

myPi = pBest/qBest;

Algorithm: Finding the best in a set
Init bestSoFar
Loop over set
    if current is better than bestSoFar
        bestSoFar ← current
    end
end
Analyze the program for efficiency

- See Eg3_1 and FasterEg3_1 in the book

```matlab
for a = 1:n
    disp('alpha')
    for b = 1:m
        disp('beta')
    end
end
```

How many times are “alpha” and “beta” displayed?

A: n, m  
B: m, n  
C: n, n+m  
D: n, n*m  
E: m*n, m
Built-in functions

- We’ve used many Matlab built-in functions, e.g., `rand`, `abs`, `floor`, `rem`

- Example: `abs(x -.5)`

- Observations:
  - `abs` is set up to be able to work with any valid data
  - `abs` *doesn’t prompt us for input; it expects that we provide data* that it’ll then work on
  - `abs` *returns* a value that we can use in our program

```matlab
yDistance = abs(y2-y1);
while abs(myPi-pi) > .0001
    ...
```
User-defined functions

- We can write our own functions to perform a specific task
  - Example: draw a disk with specified radius, color, and center coordinates
  - Example: generate a random floating point number in a specified interval
  - Example: convert polar coordinates to x-y (Cartesian) coordinates
Draw a bulls eye figure with randomly placed dots

- Dots are randomly placed within concentric rings
- User decides how many rings, how many dots
Draw a bulls eye figure with randomly placed dots

- What are the main tasks?
- Accommodate variable number of rings—loop

- For each ring
  - Need many dots

- For each dot
  - Generate random position
  - Choose color
  - Draw it
Convert from polar to Cartesian coordinates

Polar coordinates

Cartesian coordinates
c = input('How many concentric rings? ');
d = input('How many dots? ');

% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
    % Draw d dots
    for count= 1:d
        % Generate random dot location (polar coord.)
        theta= _______
r= _______
        % Convert from polar to Cartesian
        x= _______
y= _______
        % Use plot to draw dot
    end
end

A common task! Create a function polar2xy to do this. polar2xy likely will be useful in other problems as well.
c = input('How many concentric rings? ');
d = input('How many dots? ');

% Put dots btwn circles with radii rRing and (rRing-1)
for rRing= 1:c
    % Draw d dots
    for count= 1:d

        % Generate random dot location (polar coord.)
        theta= _______
        r= _______

        % Convert from polar to Cartesian
        [x,y] = polar2xy(r,theta);

        % Use plot to draw dot
    end
end
end
% Generate random dot location (polar)
theta= _____
r= __________

% Convert from polar to Cartesian
rads= theta*pi/180;  % radian
x= r*cos(rads);
y= r*sin(rads);
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads = theta*pi/180; % radian
x = r*cos(rads);
y = r*sin(rads);
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.
rads = theta*pi/180;  % radian
x = r*cos(rads);
y = r*sin(rads);

Think of polar2xy as a factory
function [x, y] = polar2xy(r,theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads= theta*pi/180;  % radian
x= r*cos(rads);
y= r*sin(rads);

r= input(‘Enter radius: ’);
theta= input(‘Enter angle in degrees: ’);

rads= theta*pi/180;  % radian
x= r*cos(rads);
y= r*sin(rads);
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y).
% theta is in degrees.

rads = theta*pi/180;  % radian
x = r*cos(rads);
y = r*sin(rads);

r = input('Enter radius: ') ;
theta = input('Enter angle in degrees: ') ;

rads = theta*pi/180;  % radian
x = r*cos(rads);
y = r*sin(rads);
c = input('How many concentric rings? ');
d = input('How many dots? ');

% Put dots btwn circles with radii rRing and (rRing-1)
for rRing = 1:c
    % Draw d dots
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        theta = _______
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A common task! Create a function polar2xy to do this. polar2xy likely will be useful in other problems as well.
c = input('How many concentric rings? ');
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% Put dots btwn circles with radii rRing and (rRing-1)
for rRing = 1:c
    % Draw d dots
    for count = 1:d
        % Generate random dot location (polar coord.)
        theta = _______
        r = _______

        % Convert from polar to Cartesian
        [x, y] = polar2xy(r, theta);

        % Use plot to draw dot
    end
end
function \[x, y] = polar2xy(r,\theta)\]

- **Function name** (This file’s name is `polar2xy.m`)
- **Input parameter list enclosed in** ( )
- **Output parameter list enclosed in** [ ]
Function header is the “contract” for how the function will be used (called)

You have this function:

```matlab
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r, theta) to
% Cartesian coordinates (x,y). Theta in degrees.
...
```

Code to call the above function:

```matlab
% Convert polar (r1,t1) to Cartesian (x1,y1)
r1 = 1; t1 = 30;
[x1, y1] = polar2xy(r1, t1);
polar2xy(r1, t1);
plot(x1, y1, 'b*')
...
```
Function header is the “contract” for how the function will be used (called)

You have this function:

```matlab
function [x, y] = polar2xy(r, theta)
% Convert polar coordinates (r,theta) to
% Cartesian coordinates (x,y). Theta in degrees.
...
```

Code to call the above function:

```matlab
% Convert polar (r1,t1) to Cartesian (x1,y1)
r1 = 1; t1 = 30;
[x1, y1] = polar2xy(r1, t1);
polar2xy(r1, t1);
plot(x1, y1, 'b*')
...
```
dotsInRings.m

(functions with multiple input parameters)
(functions with a single output parameter)
(functions with multiple output parameters)
(functions with no output parameter)